

# Local Regularity for Minimizers of Obstacle Problems of Some Anisotropic Integral Functionals

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## Abstract

A local regularity result is obtained for minimizers  $u \in \mathcal{K}_\psi = \{u \in W_{loc}^{1,(q_i)}(\Omega) : u \geq \psi\}$ ,  $q_i > 1, \forall i = 1, \dots, N$ , of anisotropic integral functionals of the type

$$\mathcal{F}(u; \Omega) = \int_{\Omega} f(x, u, Du) dx,$$

where the Carathéodory function  $f(x, u, Du) = f_0(x, u, Du) + f_1(x, u, Du)$ ,  $f_0(x, s, z)$  grows like  $\sum_{i=1}^N |z_i|^{q_i}$ , and  $f_1(x, s, z)$  satisfies some controllable growth condition.

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## 1 Introduction and Statement of Result.

Let  $\Omega \subset \mathbb{R}^N$ ,  $N \geq 2$ , be a domain. Let  $q_i > 1$ ,  $i = 1, \dots, N$ . We denote

$$q = \max_{1 \leq i \leq N} q_i, \quad p = \min_{1 \leq i \leq N} q_i \quad \text{and} \quad \bar{q} : \frac{1}{\bar{q}} = \frac{1}{N} \sum_{i=1}^N \frac{1}{q_i}.$$

Throughout this paper we will make use of the anisotropic Sobolev space

$$W_{loc}^{1,(q_i)}(\Omega) = \left\{ v \in L_{loc}^{1,q}(\Omega) : \frac{\partial v}{\partial x_i} \in L_{loc}^{q_i}(\Omega), \forall i = 1, \dots, N \right\}.$$

We consider integral functionals of the type

$$\mathcal{F}(u; \Omega) = \int_{\Omega} f(x, u, Du) dx, \tag{1.1}$$

where the Carathéodory function  $f(x, s, z)$  satisfies the following assumptions:

(i)  $f(x, s, z) : \Omega \times \mathbb{R} \times \mathbb{R}^n \rightarrow \mathbb{R}$  can be written as

$$f(x, s, z) = f_0(x, s, z) + f_1(x, s, z);$$

(ii)  $f_0(x, s, z)$  satisfies the growth condition

$$L^{-1} \sum_{i=1}^N |z_i|^{q_i} \leq f_0(x, s, z) \leq L \sum_{i=1}^N |z_i|^{q_i} + \varphi_1,$$

where  $L > 1, q_i > 1, \forall i = 1, \dots, N$ , and  $\varphi_1 \in L_{loc}^r(\Omega), 1 < r < \frac{N}{p}$ ;

(iii) there exist  $0 \leq m_i < p_i, 0 \leq h_i(x) \in L_{loc}^{\frac{q_i r}{q_i - m_i}}(\Omega), i = 1, \dots, N$ , such that

$$|f_1(x, s, z)| \leq \sum_{i=1}^N h_i(x) |z_i|^{m_i}.$$

Let  $\psi \in W_{loc}^{1,(q_i r)}(\Omega)$  and  $\mathcal{K}_{\psi} = \{u \in W_{loc}^{1,(q_i)}(\Omega) : u \geq \psi\}$ . In the present paper we shall consider minimizers  $u \in \mathcal{K}_{\psi}$  for obstacle problems of (1.1), that is,

$$\mathcal{F}(u, \text{supp}(u - v)) \leq \mathcal{F}(v, \text{supp}(u - v)) \tag{1.2}$$

for every  $v \in \mathcal{K}_{\psi}$ . The main result is the following theorem.

**Theorem 1.1** *Assume that the integral function (1.1) satisfies conditions (i), (ii) and (iii). Let  $\psi \in W_{loc}^{1,(q_i r)}(\Omega)$ . If  $u \in \mathcal{K}_{\psi}$  satisfies (1.2), then it belongs to  $L_{loc}^s(\Omega)$ , where  $s = \frac{\bar{q}^* q}{q - \bar{q}^*(1 - 1/r)}$ .*

We refer the readers to [1-7] for some results related to local regularity properties for solutions of elliptic equations and minima of variational integrals.

## 2 Preliminary Lemmas.

For  $x_0 \in \Omega$  and  $t \in \mathbb{R}$ , we denote by  $B_t = B_t(x_0)$  the ball of radius  $t$  centred  $x_0$ . For  $k > 0$ , let

$$A_k = \{x \in \Omega : |u(x)| > k\} \text{ and } A_{k,t} = A_k \cap B_t. \tag{2.1}$$

Moreover, if  $m < n$ ,  $m^*$  is the real number satisfying  $m^* = \frac{nm}{n-m}$ .

The following two lemmas will be used in the proof of Theorem 1.1. The first lemma comes from [1, Theorem 2.2].

**Lemma 2.1** *Let  $u \in W_{loc}^{1,(q_i)}(\Omega)$ ,  $\varphi_0 \in L_{loc}^r(\Omega)$ , where  $q, \bar{q}$  and  $r$  satisfies*

$$1 < r < \frac{N}{\bar{q}}, \quad q < \bar{q}^*, \quad \bar{q} < N.$$

*Assume that the following integral estimate holds*

$$\int_{A_{k,\tau}} \sum_{i=1}^N \left| \frac{\partial u}{\partial x_i} \right|^{q_i} dx \leq c_0 \left[ \int_{A_{k,t}} \varphi_0 dx + (t - \tau)^{-\alpha} \int_{A_{k,t}} \sum_{i=1}^N |u|^{q_i} dx \right] \tag{2.2}$$

*for every  $k \in \mathcal{N}$  and  $R_0 \leq \tau < t \leq R_1$ , where  $c_0$  is a positive constant that depends only on  $N, q_i, r, R_0, R_1$  and  $|\Omega|$ , and  $\alpha$  is a real positive constant. Then  $u \in L_{loc}^s(\Omega)$ , where  $s = \frac{\bar{q}^* q}{q - \bar{q}^*(1-1/r)}$ .*

The following lemma can be found in [8, p.161, Lemma 3.1].

**Lemma 2.2** *Let  $f(\tau)$  be a non-negative bounded function defined for  $0 \leq R_0 \leq t \leq R_1$ . Suppose that for  $R_0 \leq \tau < t \leq R_1$  we have*

$$f(\tau) \leq A(t - \tau)^{-\alpha} + B + \theta f(t), \tag{2.3}$$

*where  $A, B, \alpha, \theta$  are non-negative constants, and  $\theta < 1$ . Then there exist a constant  $c$ , depending only on  $\alpha$  and  $\theta$  such that for every  $\rho, R, R_0 \leq \rho < R \leq R_1$ , we have*

$$f(\rho) \leq c[A(R - \rho)^{-\alpha} + B]. \tag{2.4}$$

## 3 Proof of Theorem 1.1.

In the sequel the letter  $c$  will stands for a genetic constant which may vary from line to line. Let  $B_{R_1} \subset \subset \Omega$  and  $0 \leq R_0 \leq \tau < t \leq R_1, R_1 - R_0 \leq 1$ , be arbitrarily fixed. Let

$$T_\psi = \max\{T_k(u), \psi\},$$

where

$$T_k(u) = \max \{-k, \min\{k, u\}\}$$

is the usual truncation of  $u$  at level  $k > 0$ . Choose  $v = u - \eta(u - T_\psi)$  in (1.2), where  $\eta$  is a cut-off function such that

$$\eta \in C_0^\infty(B_t), 0 \leq \eta \leq 1, \eta = 1 \text{ in } B_\tau \text{ and } |D\eta| \leq 2(t - \tau)^{-1}.$$

For  $u \in \mathcal{K}_\psi$ , from  $\psi \in W_{loc}^{1,(q_i r)}(\Omega)$  and

$$v = u - \eta(u - T_\psi) = (1 - \eta)u + \eta T_\psi \geq (1 - \eta)\psi + \eta\psi = \psi,$$

we know that  $v \in \mathcal{K}_\psi$ . (1.2) implies

$$\begin{aligned} & \int_{B_t} f(x, u, Du) dx \leq \int_{B_t} f(x, v, Dv) dx \\ &= \int_{A_{k,t}} f(x, u - \eta(u - T_\psi), Du - D(\eta(u - T_\psi))) dx + \int_{B_t \cap \{|u| \leq k\}} f(x, u, Du) dx, \end{aligned} \tag{3.1}$$

from which we derive

$$\int_{A_{k,t}} f(x, u, Du) dx \leq \int_{A_{k,t}} f(x, u - \eta(u - T_\psi), Du - D(\eta(u - T_\psi))) dx. \tag{3.2}$$

Using (i), (ii) in (3.2) we have

$$\begin{aligned} & L^{-1} \int_{A_{k,t}} \sum_{i=1}^N \left| \frac{\partial u}{\partial x_i} \right|^{q_i} dx \\ & \leq \int_{A_{k,t}} f(x, u - \eta(u - T_\psi), Du - D(\eta(u - T_\psi))) dx - \int_{A_{k,t}} f_1(x, u, Du) dx \\ & \leq \int_{A_{k,t} \setminus A_{k,\tau}} f(x, (1 - \eta)u + \eta T_\psi, (1 - \eta)Du - (u - T_\psi)D\eta + \eta DT_\psi) dx \\ & \quad + \int_{A_{k,\tau}} f(x, T_\psi, DT_\psi) dx - \int_{A_{k,t}} f_1(x, u, Du) dx \\ & \leq \int_{A_{k,t} \setminus A_{k,\tau}} f_0(x, (1 - \eta)u + \eta T_\psi, (1 - \eta)Du - (u - T_\psi)D\eta + \eta DT_\psi) dx \\ & \quad + \int_{A_{k,t} \setminus A_{k,\tau}} f_1(x, (1 - \eta)u + \eta T_\psi, (1 - \eta)Du - (u - T_\psi)D\eta + \eta DT_\psi) dx \\ & \quad + \int_{A_{k,\tau}} f_0(x, T_\psi, DT_\psi) dx + \int_{A_{k,\tau}} f_1(x, T_\psi, DT_\psi) dx - \int_{A_{k,t}} f_1(x, u, Du) dx \\ & = I_1 + I_2 + I_3 + I_4 + I_5. \end{aligned} \tag{3.3}$$

Using (ii), (iii) and Young's inequality,  $|I_i|$ ,  $i = 1, 2, \dots, 5$ , can be estimated respectively as follows

$$\begin{aligned} |I_1| & \leq L \sum_{i=1}^N \int_{A_{k,t} \setminus A_{k,\tau}} \left| (1 - \eta) \frac{\partial u}{\partial x_i} - (u - T_\psi) \frac{\partial \eta}{\partial x_i} + \eta \frac{\partial T_\psi}{\partial x_i} \right|^{q_i} dx + \int_{A_{k,t} \setminus A_{k,\tau}} \varphi_1 dx \\ & \leq c \sum_{i=1}^N \int_{A_{k,t} \setminus A_{k,\tau}} \left( \left| \frac{\partial u}{\partial x_i} \right|^{q_i} + (t - \tau)^{-q_i} |u|^{q_i} + \left| \frac{\partial \psi}{\partial x_i} \right|^{q_i} \right) dx + \int_{A_{k,t} \setminus A_{k,\tau}} \varphi_1 dx, \end{aligned}$$

$$\begin{aligned}
 |I_2| &\leq \sum_{i=1}^N \int_{A_{k,t} \setminus A_{k,\tau}} h_i \left| (1-\eta) \frac{\partial u}{\partial x_i} - (u - T_\psi) \frac{\partial \eta}{\partial x_i} + \eta \frac{\partial T_\psi}{\partial x_i} \right|^{m_i} dx \\
 &\leq \varepsilon \sum_{i=1}^N \int_{A_{k,t} \setminus A_{k,\tau}} \left| (1-\eta) \frac{\partial u}{\partial x_i} - (u - T_\psi) \frac{\partial \eta}{\partial x_i} + \eta \frac{\partial T_\psi}{\partial x_i} \right|^{q_i} dx \\
 &\quad + c(\varepsilon) \sum_{i=1}^N \int_{A_{k,t} \setminus A_{k,\tau}} h_i^{\frac{q_i}{q_i - m_i}} dx \\
 &\leq c\varepsilon \sum_{i=1}^N \int_{A_{k,t} \setminus A_{k,\tau}} (|\frac{\partial u}{\partial x_i}|^{q_i} + (t - \tau)^{-q_i} |u|^{q_i} + |\frac{\partial \psi}{\partial x_i}|^{q_i}) dx \\
 &\quad + c(\varepsilon) \sum_{i=1}^N \int_{A_{k,t} \setminus A_{k,\tau}} h_i^{\frac{q_i}{q_i - m_i}} dx, \\
 |I_3| &\leq L \sum_{i=1}^N \int_{A_{k,\tau}} \left| \frac{\partial \psi}{\partial x_i} \right|^{q_i} dx + \int_{A_{k,\tau}} \varphi_1 dx, \\
 |I_4| &\leq \sum_{i=1}^N \int_{A_{k,\tau}} h_i \left| \frac{\partial \psi}{\partial x_i} \right|^{m_i} dx \leq \varepsilon \sum_{i=1}^N \int_{A_{k,\tau}} \left| \frac{\partial \psi}{\partial x_i} \right|^{q_i} dx + c(\varepsilon) \int_{A_{k,\tau}} \sum_{i=1}^N h_i^{\frac{q_i}{q_i - m_i}} dx, \\
 |I_5| &\leq \sum_{i=1}^N \int_{A_{k,t}} h_i \left| \frac{\partial u}{\partial x_i} \right|^{m_i} dx \leq \varepsilon \sum_{i=1}^N \int_{A_{k,t}} \left| \frac{\partial u}{\partial x_i} \right|^{q_i} dx + c(\varepsilon) \sum_{i=1}^N \int_{A_{k,t}} h_i^{\frac{q_i}{q_i - m_i}} dx.
 \end{aligned}$$

In the above estimates we have used the facts

$$|u - T_\psi| \leq |u| \text{ and } |DT_\psi| \leq |D\psi| \text{ in } A_{k,t}.$$

Substituting the above estimates into (3.3), we arrive at

$$\begin{aligned}
 \sum_{i=1}^N \int_{A_{k,\tau}} \left| \frac{\partial u}{\partial x_i} \right|^{q_i} dx &\leq c \sum_{i=1}^N \int_{A_{k,t} \setminus A_{k,\tau}} \left( \left| \frac{\partial u}{\partial x_i} \right|^{q_i} + (t - \tau)^{-q_i} |u|^{q_i} \right) dx \\
 &\quad + c \sum_{i=1}^N \int_{A_{k,t}} \left( \varphi_1 + h_i^{\frac{q_i}{q_i - m_i}} + \left| \frac{\partial \psi}{\partial x_i} \right|^{q_i} \right) dx.
 \end{aligned}$$

Adding to both sides  $c$  times the left-side and dividing by  $1 + c$  we get

$$\begin{aligned}
 \sum_{i=1}^N \int_{A_{k,\tau}} \left| \frac{\partial u}{\partial x_i} \right|^{q_i} dx &\leq \theta \sum_{i=1}^N \int_{A_{k,t}} \left| \frac{\partial u}{\partial x_i} \right|^{q_i} dx + \frac{\theta}{(t - \tau)^q} \sum_{i=1}^N \int_{A_{k,t}} |u|^{q_i} dx \\
 &\quad + c \sum_{i=1}^N \int_{A_{k,t}} \left( \varphi_1 + h_i^{\frac{q_i}{q_i - m_i}} + \left| \frac{\partial \psi}{\partial x_i} \right|^{q_i} \right) dx,
 \end{aligned}$$

where  $\theta = \frac{c}{1+c} < 1$ . Lemma 2.2 yields that for any  $\rho$  and  $R$  with  $R_0 \leq \rho \leq \tau < t \leq R \leq R_1$ , we have

$$\begin{aligned}
 &\sum_{i=1}^N \int_{A_{k,\rho}} \left| \frac{\partial u}{\partial x_i} \right|^{q_i} dx \\
 &\leq \frac{c}{(R - \rho)^q} \sum_{i=1}^N \int_{A_{k,R}} |u|^{q_i} dx + c \sum_{i=1}^N \int_{A_{k,R}} \left( \varphi_1 + h_i^{\frac{q_i}{q_i - m_i}} + \left| \frac{\partial \psi}{\partial x_i} \right|^{q_i} \right) dx.
 \end{aligned}$$

Theorem 1.1 follows from Lemma 2.1.

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